



# CS 112/212 Section 1, Project 1: Threads

January 13th, 2023

**Goal: Extend functionality of the simple  
given thread system in Pintos**

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# Requirements

1. Alarm Clock
  - a. Re-implement `timer_sleep()` without busy waiting
2. Priority Scheduler
  - a. Threads set their own priorities, and run according to these priorities
  - b. Priority donation for locks
3. Advanced Scheduler
  - a. Thread priorities are calculated by the system, and run according to these priorities
  - b. No priority donation
4. Design Doc
  - a. Answer questions regarding your design and implementation for parts 1-3



## Grading

- 50% tests, 50% design quality (including your design doc)

# Questions?



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# 1. Alarm Clock



## Alarm Clock: Overview

- When a thread calls `timer_sleep()`, it needs to sleep for a given # of ticks
- Currently is implemented by busy waiting
- **Your job is to re-implement `timer_sleep()` without busy waiting**



## Alarm Clock: Key Questions

- How will you avoid busy waiting?
- How will you keep track of sleeping threads?
- Where in the code will you wake up sleeping threads?
- Check out the design doc to see what race conditions you should watch out for!



**Questions?**



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## 2. Priority Scheduling



## Priority Scheduling: Overview

1. Threads with higher priority should be run first (0 = minimum priority, 63 = maximum priority)
2. When threads are waiting for a lock, semaphore, or condition variable, the highest priority waiting thread should be awakened first
3. Implement priority donation for locks to partially fix priority inversion



## Priority Scheduling: Overview

1. Threads with higher priority should be run first (0 = minimum priority, 63 = maximum priority)
2. When threads are waiting for a lock, semaphore, or condition variable, the highest priority waiting thread should be awakened first
3. **Implement priority donation for locks to partially fix priority inversion**



# The Priority Inversion Problem

**Thread L**

Original priority: 1

**Lock**

Holder = NULL



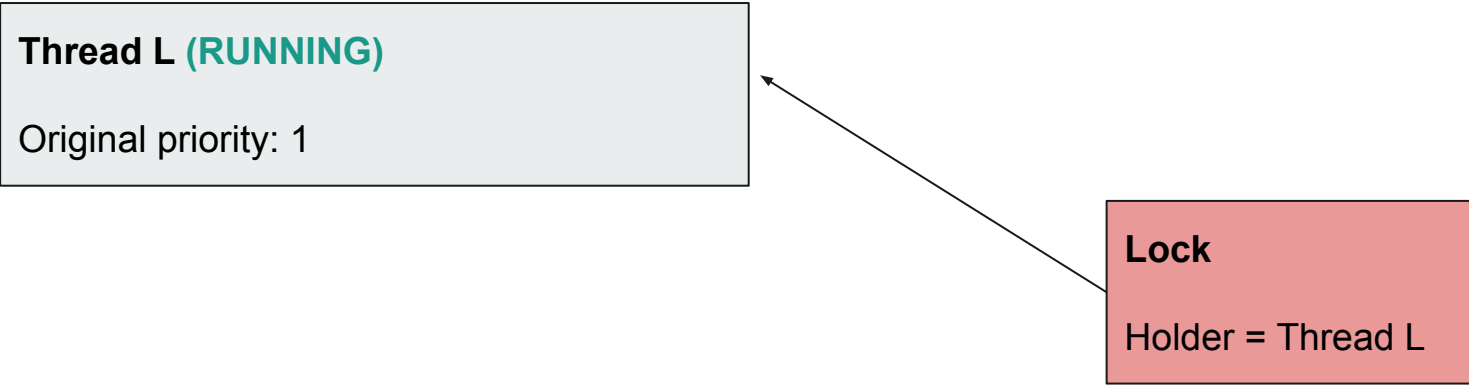
# The Priority Inversion Problem

Thread L (**RUNNING**)

Original priority: 1

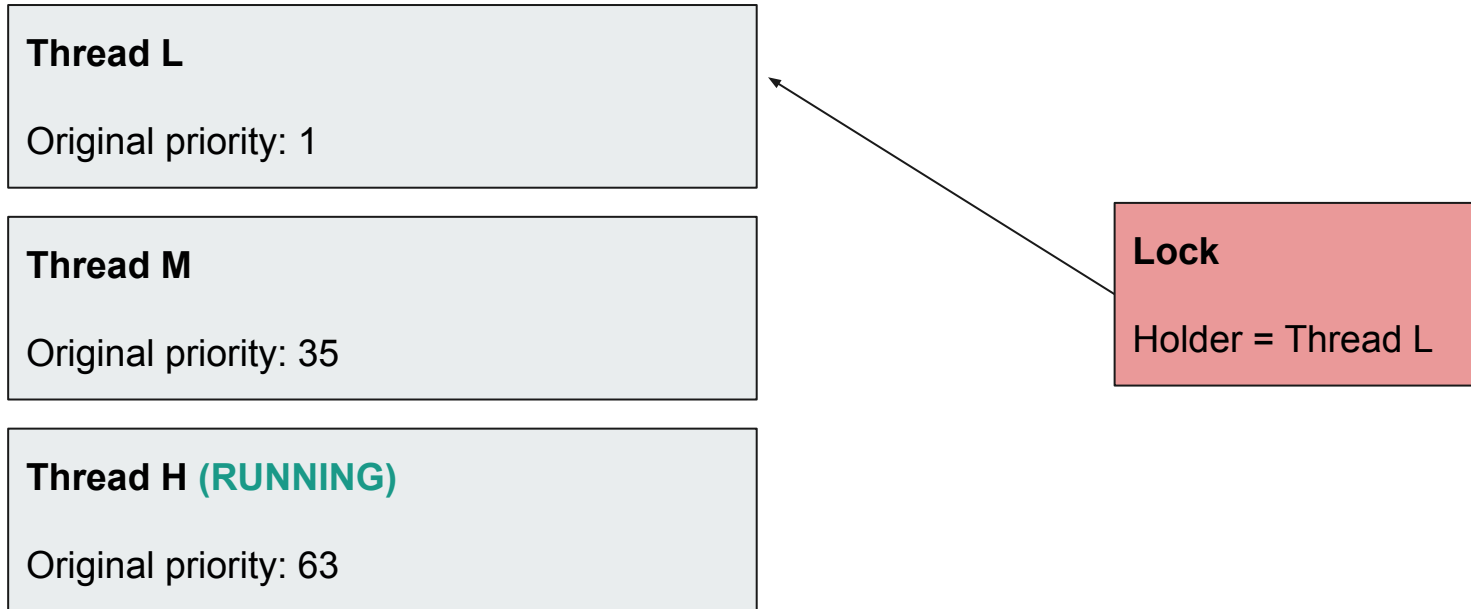
**Lock**

Holder = Thread L



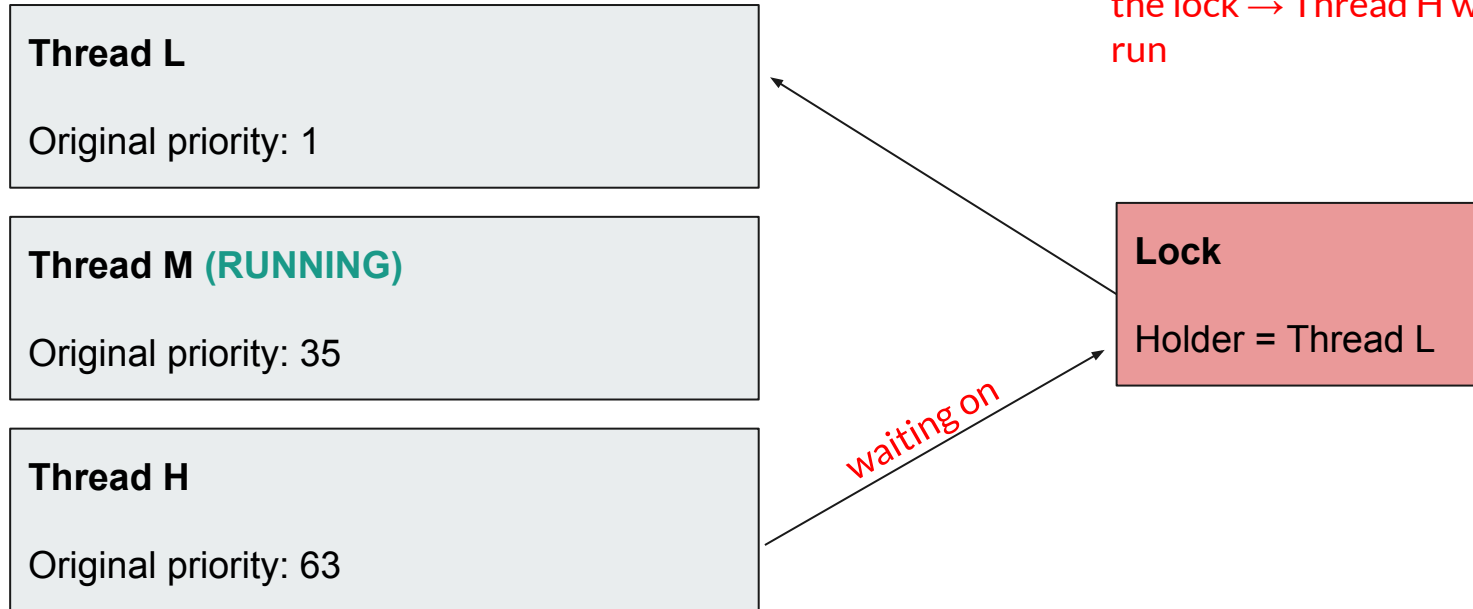


# The Priority Inversion Problem





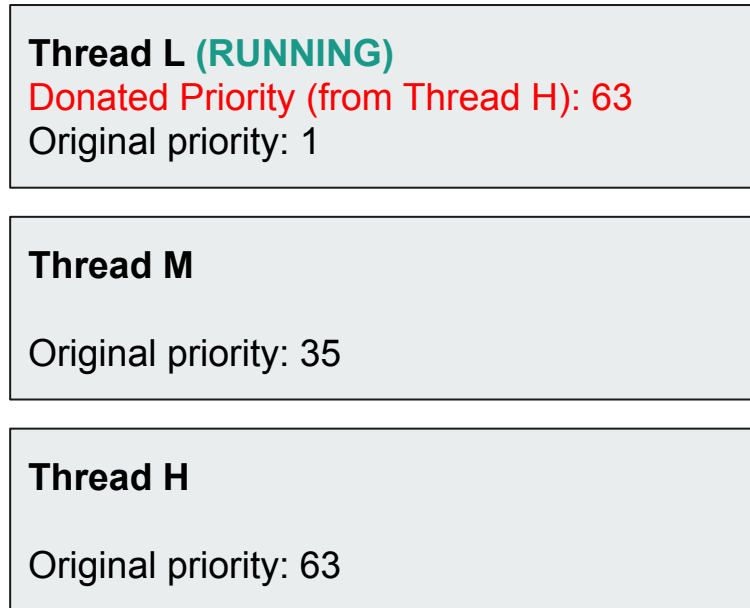
# The Priority Inversion Problem



- Thread H is taken off of CPU, because it is waiting for Lock
- Thread M will run because it has a higher priority than Thread L
- Therefore, Thread L will not release the lock → Thread H will not get to run



## Priority Donation: Example 1 (to Fix Priority Inversion)



- When Thread H tries to acquire Lock, it donates its priority to Thread L
- Now, Thread L will get to run



## Priority Donation: Example 1

**Thread L**

Original priority: 1

**Thread M**

Original priority: 35

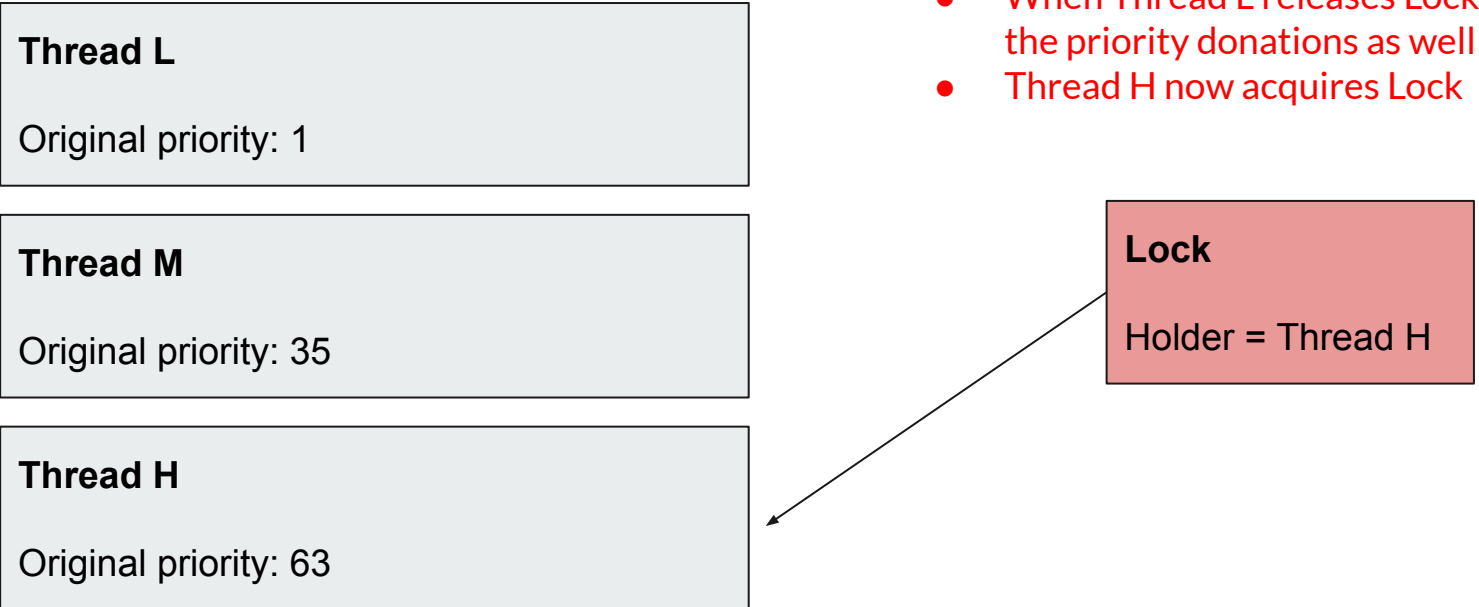
**Thread H**

Original priority: 63

- When Thread L releases Lock, it releases the priority donations as well
- Thread H now acquires Lock

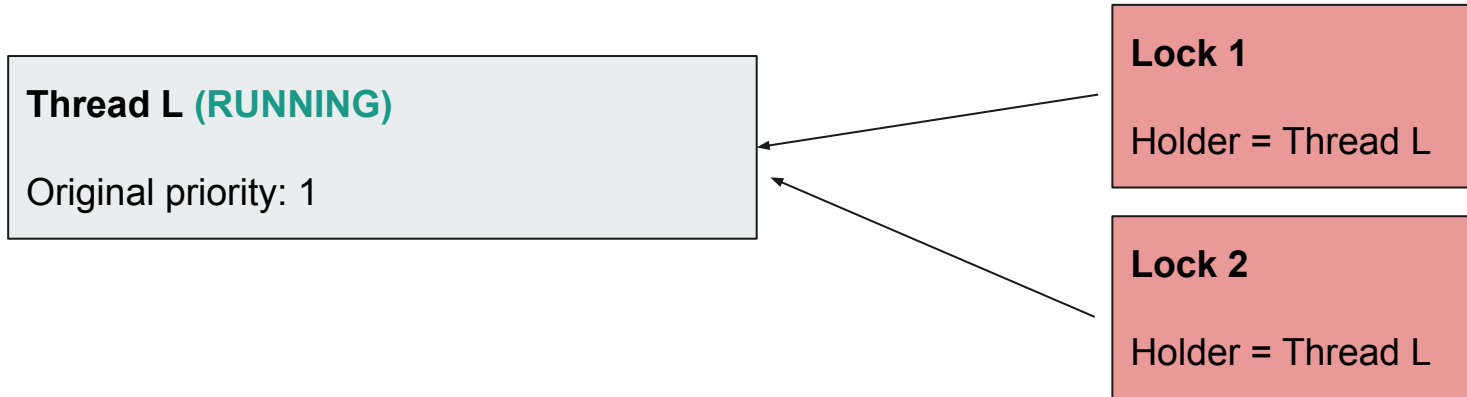
**Lock**

Holder = Thread H



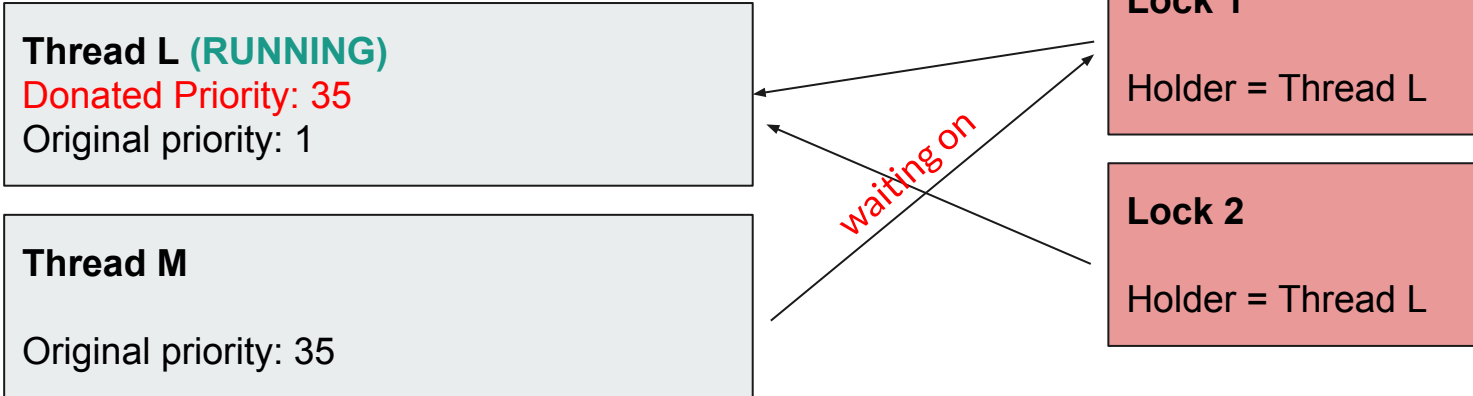


## Priority Donation Example 2: Multiple Donations



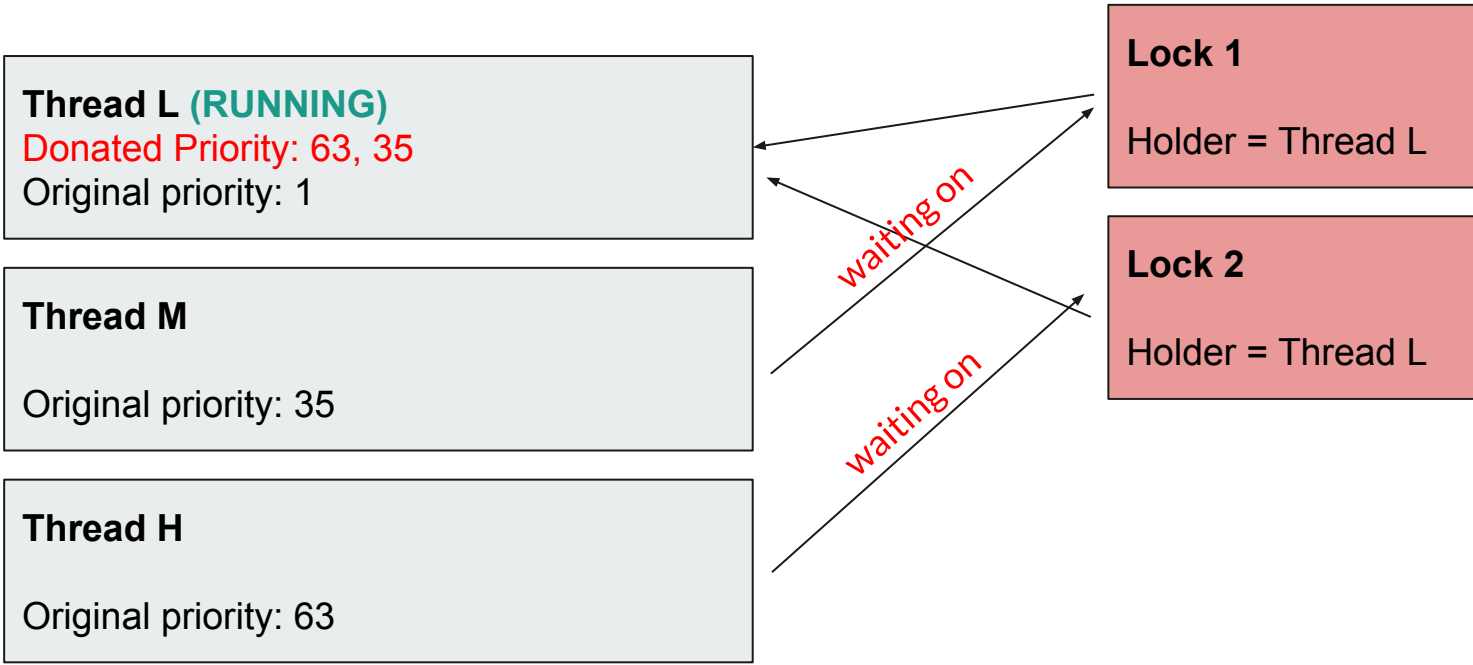
Thread M tries to acquire Lock 1, so donates its priority to Thread L

# Priority Donation Example 2: Multiple Donations



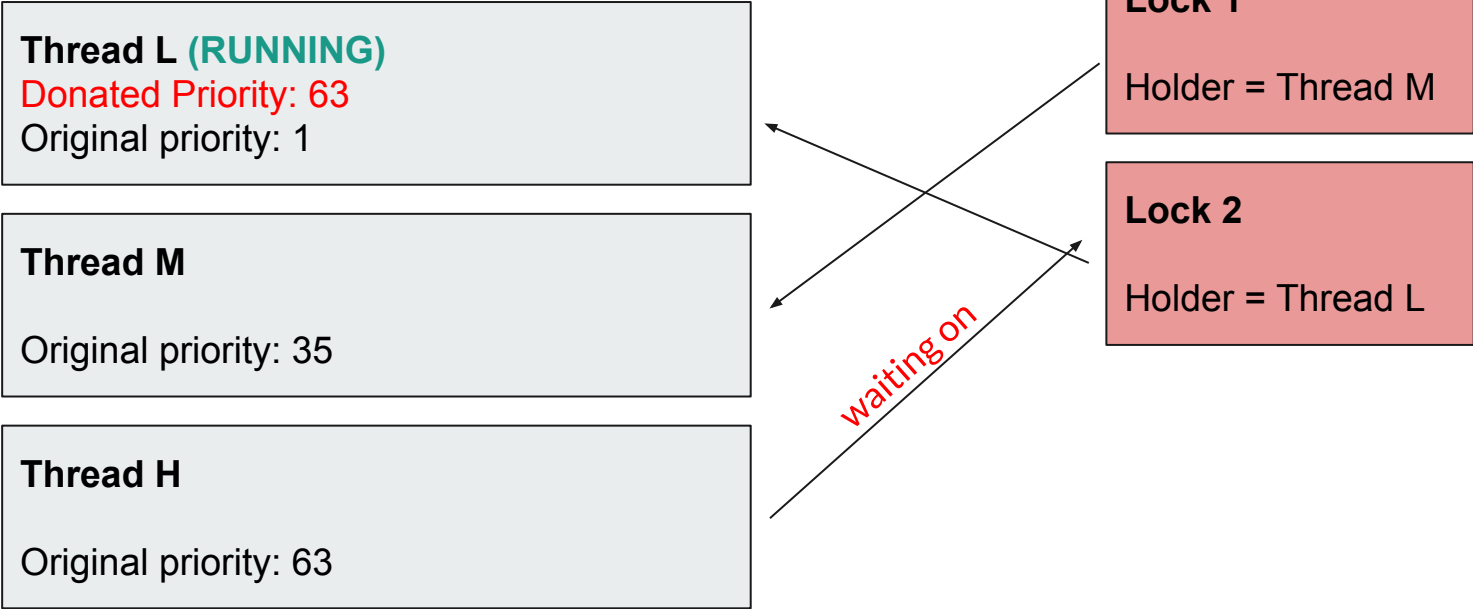
Thread H tries to acquire Lock 2, so donates its priority to Thread L

# Priority Donation Example 2: Multiple Donations



Thread L releases Lock 1 and gives back its donation

# Priority Donation Example 2: Multiple Donations



Thread L releases Lock 2 and gives back its donation

# Priority Donation Example 2: Multiple Donations

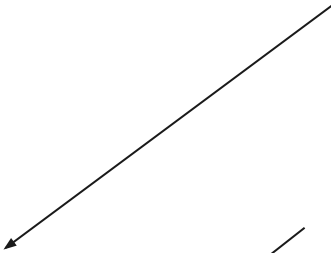
**Thread L**  
Original priority: 1

**Thread M**  
Original priority: 35

**Thread H (RUNNING)**  
Original priority: 63

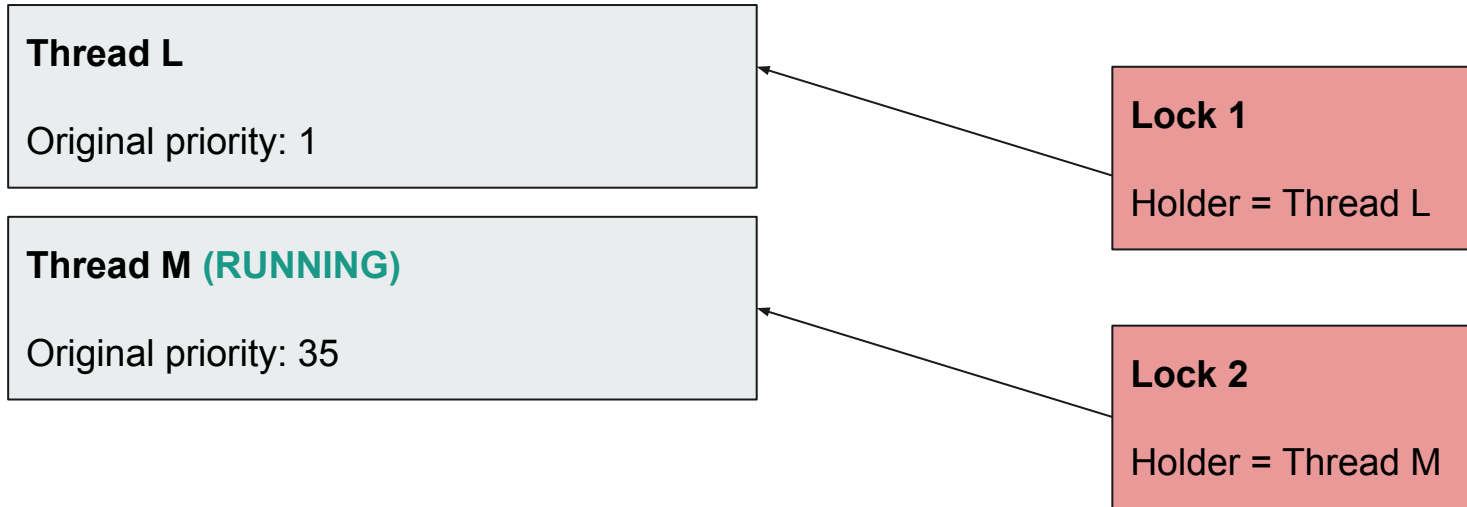
**Lock 1**  
Holder = Thread M

**Lock 2**  
Holder = Thread H



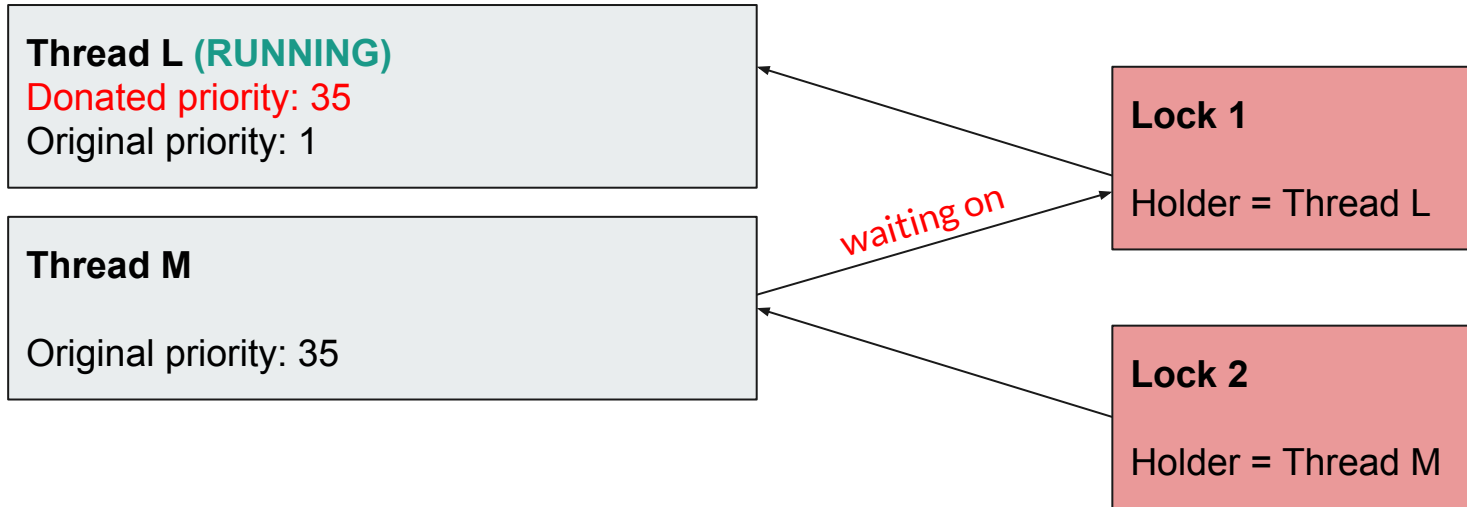


## Priority Donation Example 3: Nested Donations



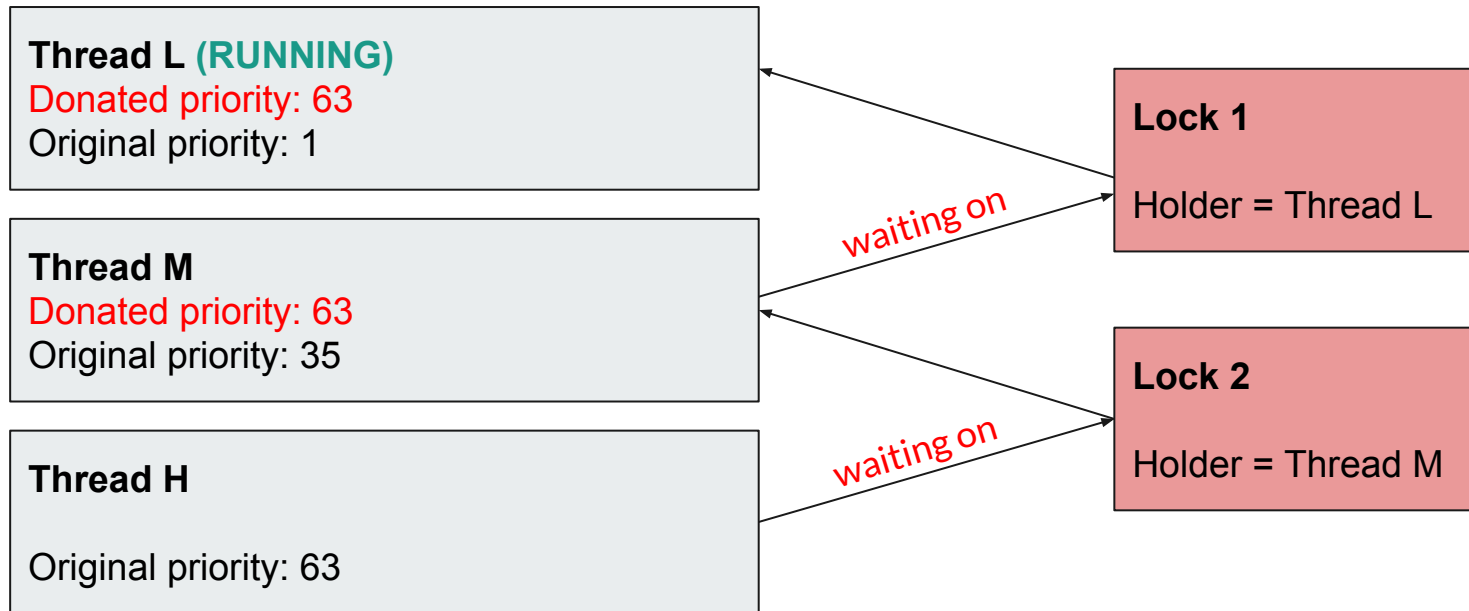


## Priority Donation Example 3: Nested Donations



Note: You may impose a reasonable limit on depth of nested priority donation, such as 8 levels

## Priority Donation Example 3: Nested Donations





## Priority Scheduler: Key Questions

- What data structure will you use to track priority donations?
- When are priority donations given, and when are they returned?
- How will you ensure that the highest priority thread waiting for a lock, semaphore, or condition variable is woken up?

# Questions?



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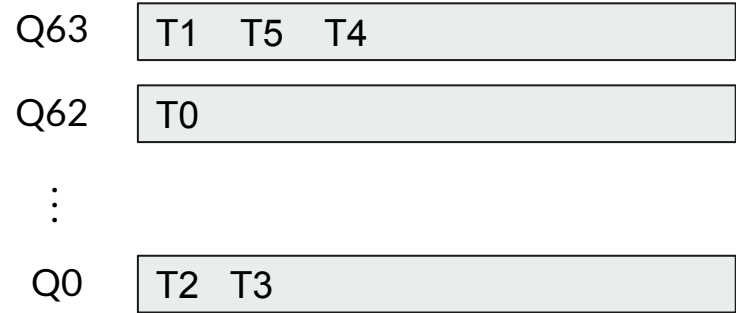
## 3. Advanced Scheduler



# Advanced Scheduler: Overview

(a multilevel feedback queue scheduler)

- Scheduler chooses a thread from the highest-priority non-empty queue
- If the highest-priority queue contains multiple threads, then they run in "round robin" order





# Advanced Scheduler: Overview

- Thread priority is dynamically determined by the scheduler using a formula given below, recalculated once every fourth timer tick for every thread for which `recent_cpu` has changed
  - $priority = PRI\_MAX - (recent\_cpu / 4) - (nice * 2)$
  - Detailed explanations of how/when to calculate `recent_cpu` and `nice` are here: [B.4.4BSD Scheduler](#)
  - No priority donation
- We recommend that you have the priority scheduler working, except possibly for priority donation, before you start work on the advanced scheduler



## Advanced Scheduler: Fixed Point Math

- Calculations for the advanced scheduler involve both integers and real numbers
- Floating-point arithmetic in the kernel would complicate and slow the kernel → Pintos and other real kernels do not support it → calculations on real quantities must be simulated using integers
- **You will have to carefully implement fixed point arithmetic to perform calculations for your advanced scheduler**



# Questions?



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## 4. Design Doc



# Design Doc

- Read through the design doc first – it will help you understand the important design problems you need to solve
- **Remember: design quality, including the design doc, is 50% of your project grade!!!  
Do not wait until the last minute to write it.**

# Questions?



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# Getting Started



# Getting Started

- Make sure to read the spec thoroughly, including FAQs!
- Design/style is important - make sure to write a good design doc.
- Directories you will be working in: src/threads, src/devices
- A good hint for where to start reading code (summary of reference solution changes from the spec):

```
devices/timer.c      | 42 ++++-  
threads/fixed-point.h | 120 +++++  
threads/synch.c     | 88 +++++-  
threads/thread.c    | 196 +++++-----  
threads/thread.h    | 23 +++  
5 files changed, 440 insertions(+), 29 deletions(-)
```

- Check out lib and lib/kernel for useful library routines!



## General Advice

- Start early!
- Integrate code changes early and often (do NOT just divide tasks and combine code last minute!)
- Spend time reading code BEFORE writing any code!
- **Pay attention and conform to the style of the given code!!!**