

Why disk arrays?

- **CPUs improving faster than disks**
 - disks will increasingly be bottleneck
- **New applications (audio/video) require big files (motivation for XFS)**
- **Disk arrays - make one logical disk out of many physical disks**
- **More disks results in two benefits**
 - Higher data transfer rates on large data accesses
 - Higher I/O rates on small data accesses

Reliability implications of arrays

- **JBOD array with 100 disks is 100 times more likely to fail!**
 - Each disk 200,000 hours MTBF → array 2,000 hours (3 months)
[approximately – double counts two disks failing]
- **Use redundancy to improve reliability**
 - But makes writes slower, since redundant info must be updated
 - Raises issues of consistency in the face of power failures

Disk array basics

- **Data striping - balances load across disks**
- **Redundancy - improve reliability**
- **Many different schemes, depending on**
 - granularity of data interleaving
 - fine grained → high transfer rates for all requests
 - course grained → allow parallel small requests to different disks
 - method in which redundant information computed & distributed

RAID 0

- **Nonredundant storage (JBOD - just a bunch of disks)**
 - E.g., Stripe sequential 128K logical regions to different disk
- **Offers best possible write performance (only one write per write)**
- **Offers best possible storage efficiency (no redundancy)**
- **Offers good read performance**
- **Use if speed more important than reliability (scientific computing)**

RAID 1

- **Mirrored storage** – Each block stored on two disks
- **Writing slower** (twice as many operations)
- **Storage efficiency 1/2** optimal
- **Small reads better than other scheme**
 - can read on disk with shortest seek

RAID 2

- Use Hamming codes, like ECC memory

- Multiply data by generator matrix $G = (I \ A)$

$$G = \begin{pmatrix} 1 & 0 & 0 & 0 & 1 & 1 & 1 \\ 0 & 1 & 0 & 0 & 0 & 1 & 1 \\ 0 & 0 & 1 & 0 & 1 & 0 & 1 \\ 0 & 0 & 0 & 1 & 1 & 1 & 0 \end{pmatrix}$$

$$D = (d_1 \ d_2 \ d_3 \ d_4)$$

$$E = G \times D = \begin{pmatrix} d_1 \\ d_2 \\ d_3 \\ d_4 \\ d_1 + d_3 + d_4 \\ d_1 + d_2 + d_4 \\ d_1 + d_2 + d_3 \end{pmatrix}$$

hamming codes (continued)

- Decode by multiplying by $H = (A^T \quad I)$

$$H = \begin{pmatrix} 1 & 0 & 1 & 1 & 1 & 0 & 0 \\ 1 & 1 & 0 & 1 & 0 & 1 & 0 \\ 1 & 1 & 1 & 0 & 0 & 0 & 1 \end{pmatrix}$$

$$H \times E = (d_1 \quad d_2 \quad d_3 \quad d_4 \quad 0 \quad 0 \quad 0)$$

- Can recover any two missing bits
- Can even recover from one incorrect bit!
 - If one extra bit is 1, it is wrong
 - If two extra bits are 1, d_2 , d_3 , or d_4 is wrong
 - If all 3 extra bits are 1, d_1 is wrong

Properties of RAID 2

- **Small reads about like RAID 0**
 - Though more contention for data disks
- **Writes must update multiple parity disks**
- **Storage more efficient than RAID 1 (uses more than half of disks)**
- **Recovers from errors (RAID 1 assumes fail-stop)**
 - Is this overkill?
 - Most disks are fail-stop

RAID 3

- Bit interleaved parity
- Assume fail stop disks, add one parity disk

$$D = (d_1 \ d_2 \ d_3 \ d_4)$$

$$E = (d_1 \ d_2 \ d_3 \ d_4 \ d_1 + d_2 + d_3 + d_4)$$

- Any read touches all data disks
- Any write touches all data disks plus parity disk

RAID 4

- **Block-interleaved parity**
- **Interleave data in blocks instead of bits**
- **Reads smaller than striping unit can access only one disk**
- **Writes must update data and compute and update parity block**
 - Small writes require **two reads plus two writes**
 - Heavy contention for parity disk (all writes touch it)

RAID 5

- **Block-interleaved *distributed* parity**
 - Distribute parity uniformly over all the disks
 - Want to access disks sequentially when sequentially accessing logical blocks:

0	1	2	3	p_0
5	6	7	p_1	4
10	11	p_2	8	9
15	p_3	12	13	14
p_4	16	17	18	19
- **Better load balancing than RAID 4**
- **Small writes still require read-modify-write**

RAID 6

- **P+Q Redundancy (rarely implemented)**
 - Have two parity blocks instead of one
 - With Reed-Solomon codes, can lose any two blocks
- **Now must read-modify-write two parity blocks plus data**

RAID Summary

RAID level	SmRd	SmWr	BigRd	BigWr	Space
0	1	1	1	1	1
1	1	1/2	1	1/2	1/2
3	1/G	1/G	(G-1)/G	(G-1)/G	(G-1)/G
5	1	$\max(1/G, 1/4)$	1	(G-1)/G	(G-1)/G
6	1	$\max(1/G, 1/6)$	1	(G-2)/G	(G-2)/G

- RAID 4 is strictly inferior to RAID 5
- RAID 2 inferior to RAID 5 for fail-stop disks
- RAID 1 is just RAID 5 with parity group size G=2
- RAID 3 is just like RAID 5 with a very small stripe unit

When/how do disks fail?

- Disks can fail very early in their lifetimes (manufacturing errors)
- Also tend to fail late in their lifetimes (when disk wears out)
- Systematic manufacturing defect can make entire batch of disks fail early
 - Beware disks with consecutive serial numbers!
- Environmental factors can kill a bunch of disks (air conditioning failure)
- Disks can fail when a bad block is read Bad block may exist for a while before being detected

Dealing with failures

- **Basic idea:**
 - Add new disk
 - Reconstruct failed disk's state on new disk
- **Must store metadata information during recovery**
 - Which disks are failed?
 - How much of failed disk has been reconstructed?
- **System crashes become very serious in conjunction with disk failure**
 - Parity may be inconsistent (particularly bad for P+Q)
 - You could lose a block other than the one you were writing
 - MUST log in NVRAM enough info to recover parity
 - Makes software-only implementation of RAID risky

Maximizing availability

- Want to keep operating after failure
- Demand reconstruction
 - Assumes spare disk immediately (or already) installed
 - Reconstruct blocks as accessed
 - Background thread reconstructs all blocks
- Parity sparing
 - Replaces parity block with reconstructed data block
 - Need extra metadata to keep track of this

Unrecoverable RAID failures

- Double disk failures (or triple, if P+Q redundancy)
- System crash followed by disk failure
- Disk failure, then read and discover bad block during reconstruction

RAID improvements

- **Parity logging**

- Log difference of old and new parity blocks
- Delay updating actual parity
- Further writes may save you from a read

- **Declustered parity**

- Many parity groups, spread over many disks

- **Parity sparing**

- Use spare disks to improve performance by spreading load

Tuning RAID

- **What is optimal size of data stripe in RAID 0 disk array?**

$$\sqrt{(P X (L - 1) Z) / N}$$

- **P** - average positioning time
- **X** - disk transfer rate
- **L** - concurrency of workload
- **Z** - request size
- **N** - size of array in disks

- **What about in RAID 5?**

- Reads - similar to RAID 0
- Writes - optimal is a factor of 4 smaller than for reads (for 16 disks)
- Seems to vary WITH #disks, while reads vary inversely!

- **Conclusion: Very workload dependent!**